MAGNETIC TOOLS

Model KE-D'E ELECTRO MAGNETIC HOLDER



KF-4F

KE-3E

Max.Holding

18N (1.8kgf)

80N (8kgf)

220N (22kgf)

Power

Plate Thickness

(N)

300

250

200

150

100 50

n

Model

KE-2D

100

80

60

40

20

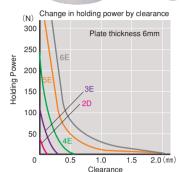
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Holding Powe

Holding Power

Controller required additionally



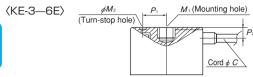


[Application]

Thin type electromagnetic holders suitable for a robotic hand as they provide vertical motion in a certain range in

[Features]

- Special cables that have specially high durability against bending and vibration are used. (Employed in all models except for KF-2D.)
- Usable for continuous operation.
- Finished by plating.



Non-watertight

Precaution for use

90 VDC

0.065A

Rust and scratches on the attractive face affect the holding power adversely. Repair it periodically.

Power Cord Working Voltage Current Applicable Rectifie Mass С Rate 0.04 A 30g/0.06 lb KR-T101-6/24 RH-M303A-6/24, -C1, -C2 7.5 (0.29 0.085A 100g/0.22 lb 100% RH-M105A-24 8 (0.31 0.12 A ED 190g/0.42 lb φ3.7 380g/0.83 lb 9.5 (0.37) 0.0444

*E type: Cord length 0.3 m (0.2-m lead for KE-2D only) *The maximum holding power applies to SS400, 10-mm thick, ground-finished test piece held on the whole area

(0.19) Depth 4 (0.15) 20 (0.78)

500g/1 10 lb 1N≒0.1kgf

Dimensions

 $\phi 20(0.78) \times 25(0.98)$

KE-6E $\phi 60(2.36) \times 30(1.18)$ 880N(90kgf)

KE-3E ϕ 30 (1.18) \times 25 (0.98)

KE-4E $\phi 40(1.57) \times 25(0.98)$

ELECTRO MAGNETIC HOLDER

Change in holding power by clearance

Plate thickness 4mm

φ5

Hole Dimensions

Mo

φ2.1 (0.08) Depth 2.5 (0.09)

φ4 (0.15) Depth 2 (0.07)

φ4 (0.15) Depth 2.5 (0.09)

7.5 (0.29

10 (0.39)

15 (0.59)



(N) 120

100

80

60

Holding Power

5 (mm)

 M_1

 $M4(0.15) \times 0.7(0.02)$

Depth 8 (0.31)

M6(0.23) ×1.0(0.03)

Depth12(0.47)

Depth15 (0.59)

490N (50kgf) M8 (0.31) ×1.25 (0.04) φ5 (0.19) Depth 3 (0.11

[Application]

11 (0.43)

Small and light, for meeting uses in carrying press material which is not easily released by its own weight; also for holding hands of industrial robots.

- Special cables that have specially high durability against bending and vibration are used. (Employed in all models except for KE-2R.)
- ●The workpiece is released quickly by the spring pressure of the projection at the center of the attractive face. The spring pressure can be adjusted according to workpiece situations.
- Electrical control such as a reverse exciting circuit is not necessary.
- Quick attach and detach enables speedy automation.
- Usable for continuous operation.
- Finished by plating.
- *Use these holders for workpieces whose surface where the holder comes in contact is not rough. They are not suitable for thin plates that may be deformed by the pressing force.

40 20 KE-2R

KE-4RA

Change in holding power by plate thickness

3

0.1 0.2 (mm)

3RA

Precaution for use

Rust and scratches on the attractive face affect the holding power adversely. Repair it periodically

		Tiate Thickness		Olearanee					[111111(111)]
	Model	Dimensions	Max.Holding Power	Tapped Hole	Voltage	Current	Working Rate	Applicable Rectifier	Mass
	KE-2R	$\phi 20 (0.78) \times 25 (0.98)$	5N (0.5kgf)	M5(0.19) × 0.8(0.03) Depth 5(0.19)	24 VDC	0.04 A	100% ED	KR-T101A-6/24 RH-M303A-6/24、-C1、-C2 RH-M105B-24	50g/0.11 lb
1	KE-3RA	ϕ 30 (1.18) \times 25 (0.98)	30N (3kgf)	M6 (0.23) × 1.0 (0.03) Depth 6 (0.23)		0.085A			100g/0.22 lb
	KE-4RA	$\phi 40 (1.57) \times 25 (0.98)$	100N (10kgf)	M6 (0.23) × 1.0 (0.03) Depth 7.5 (0.29)		0.12 A			200g/0.44 lb
**Projection is provided at the center of attractive face with 42 X may length 1mm for KE-2R & 42.5 X may length 1mm for KE-3R and									

*If the pressing force cannot release the workpiece smoothly, use a rectifier enclosed in parentheses. **RA type: Cord length 0.3 m (0.2-m lead for KE-2R only)

*The maximum holding power applies to SS400, 10-mm thick, ground-finished test piece held on the whole area

- ※Allowable temperature: The electromagnetic holders KE, permanent electromagnetic holders KEP and hybrid holders KE-H must be used under the conditions of ambient temperature 40 °C or below and temperature of workpieces to hold 50°C or below. For higher temperature, please contact us.
- *The holding power of KE-B, KE-E (D) and KE-RA (R) on various thickness of steel plates and the holding power relative to various gaps are as shown in the graphs.
- *The maximum holding power is the power that can be obtained under the most favorable conditions including materials, shapes and finishes of workpieces to hold. Thus, for practical use, choose a suitable model in consideration of a large drop in the holding power depending on situations. Generally, the lifting capacity drops to a half or below of the holding power obtained from the graphs. If you plan to use holders in particular situations such as for workpieces having holes and grooves on the attractive face to
- disable the utilization of the whole area or where big acceleration (G) will be applied to workpieces to be held and transported, please contact us.
- *The electromagnetic holders when powered off still have residual magnetism. If the mass of the workpiece is greater than the residual holding power, the workpiece will come off, but if not, it is usually necessary to use a rectifier equipped with a reduction-of-magnetization function by reverse excitation, except for the holders equipped with the automatic release function.
- *The electromagnetic holders are not of waterproof construction. If waterproof holders are required, please contact us.
- If you want to use an uninterruptible power supply for a rectifier for electromagnetic holders, please consult with us in advance.